

# An approach to initial conditions in general relativity

J. Tafel

Institute of Theoretical Physics, Department of Physics, University of Warsaw

The 1st Conference of Polish Society of Relativity  
Spała 2014

Tafel J. 2014, An approach to initial conditions in general relativity, sent to *Class. Quantum Grav.*, arXiv: 1405.1202

Tafel J. and Jóźwikowski M. 2014, New solutions of initial conditions in general relativity, *Class. Quantum Grav.* **31** 115001, arXiv:1312.7819

# Initial data in vacuum

**Data:** the Riemannian metric  $g_{ij}$  and a symmetric tensor  $K_{ij}$  (the exterior curvature) on an initial surface  $S$ .

**Data:** the Riemannian metric  $g_{ij}$  and a symmetric tensor  $K_{ij}$  (the exterior curvature) on an initial surface  $S$ .

**Conditions:** the momentum (vector) constraint

$$\nabla_i(K^{ij} - g^{ij}H) = 0, \quad H = K_i^i$$

**Data:** the Riemannian metric  $g_{ij}$  and a symmetric tensor  $K_{ij}$  (the exterior curvature) on an initial surface  $S$ .

**Conditions:** the momentum (vector) constraint

$$\nabla_i(K^{ij} - g^{ij}H) = 0, \quad H = K_i^i$$

and the Hamiltonian (scalar) constraint

$$R + H^2 - K_{ij}K^{ij} = 0.$$

# Initial data in vacuum

**Data:** the Riemannian metric  $g_{ij}$  and a symmetric tensor  $K_{ij}$  (the exterior curvature) on an initial surface  $S$ .

**Conditions:** the momentum (vector) constraint

$$\nabla_i(K^{ij} - g^{ij}H) = 0, \quad H = K_i^i$$

and the Hamiltonian (scalar) constraint

$$R + H^2 - K_{ij}K^{ij} = 0.$$

Notation:  $T^{ij} = K^{ij} - Hg^{ij}$

# The conformal approach (Lichnerowicz, Choquet-Bruhat, York)

$$g'_{ij} = \psi^4 g_{ij}, \quad K'_{ij} = \psi^{-2} K_{ij} + \frac{1}{3} H' g_{ij}, \quad K'^i{}_i = 0$$

# The conformal approach (Lichnerowicz, Choquet-Bruhat, York)

$$g'_{ij} = \psi^4 g_{ij}, \quad K'_{ij} = \psi^{-2} K_{ij} + \frac{1}{3} H' g_{ij}, \quad K'^i_i = 0$$

The Hamiltonian constraint

$$\Delta\psi = \frac{1}{8} R\psi - \frac{1}{8} K_{ij} K^{ij} \psi^{-7} + \frac{1}{8} H'^2 \psi^5$$

is, in general, coupled to the momentum constraint.



# The conformal approach (Lichnerowicz, Choquet-Bruhat, York)

$$g'_{ij} = \psi^4 g_{ij}, \quad K'_{ij} = \psi^{-2} K_{ij} + \frac{1}{3} H' g_{ij}, \quad K'^i{}_i = 0$$

The Hamiltonian constraint

$$\Delta\psi = \frac{1}{8} R\psi - \frac{1}{8} K_{ij} K^{ij} \psi^{-7} + \frac{1}{8} H'^2 \psi^5$$

is, in general, coupled to the momentum constraint.

An exception: if  $H' = \text{const}$  then

$$\nabla_i K^{ij} = 0$$

(the momentum constraint with  $H = 0$ ).

# The conformal approach (Lichnerowicz, Choquet-Bruhat, York)

$$g'_{ij} = \psi^4 g_{ij}, \quad K'_{ij} = \psi^{-2} K_{ij} + \frac{1}{3} H' g_{ij}, \quad K'^i{}_i = 0$$

The Hamiltonian constraint

$$\Delta\psi = \frac{1}{8} R\psi - \frac{1}{8} K_{ij} K^{ij} \psi^{-7} + \frac{1}{8} H'^2 \psi^5$$

is, in general, coupled to the momentum constraint.

An exception: if  $H' = \text{const}$  then

$$\nabla_i K^{ij} = 0$$

(the momentum constraint with  $H = 0$ ). Thus, it makes sense to solve the momentum constraint first, provided that  $H$  can be set to zero.

# The momentum constraint in the Gauss coordinates

Initial metric

$$g = g_{ab}dx^a dx^b + d\varphi^2, \quad \varphi = x^3.$$

# The momentum constraint in the Gauss coordinates

Initial metric

$$g = g_{ab} dx^a dx^b + d\varphi^2, \quad \varphi = x^3.$$

The momentum constraint

$$(|\tilde{g}| T_a^3)_{,3} = -|\tilde{g}| T_{a|b}^b$$

$$(|\tilde{g}| T^{33})_{,3} = |\tilde{g}| (g_{ab,3} T^{ab} - T^{3a}{}_{|a}),$$

where

$$|\tilde{g}| = \sqrt{\det g_{ab}}.$$

# The momentum constraint in the Gauss coordinates

Initial metric

$$g = g_{ab} dx^a dx^b + d\varphi^2, \quad \varphi = x^3.$$

The momentum constraint

$$(|\tilde{g}| T_a^3)_{,3} = -|\tilde{g}| T_{a|b}^b$$

$$(|\tilde{g}| T^{33})_{,3} = |\tilde{g}| (g_{ab,3} T^{ab} - T^{3a}{}_{|a}),$$

where

$$|\tilde{g}| = \sqrt{\det g_{ab}}.$$

Problems with integration if  $H = 0$  or  $\partial_\varphi$  is a symmetry.

# Arbitrary foliation of initial manifold

Initial metric

$$g = g_{ab}dx^a dx^b + \alpha^2(d\varphi + \beta_a dx^a)^2 .$$

# Arbitrary foliation of initial manifold

Initial metric

$$g = g_{ab}dx^a dx^b + \alpha^2(d\varphi + \beta_a dx^a)^2 .$$

Basis

$$\theta^a = dx^a , \quad \theta^3 = d\varphi + \beta_a dx^a$$

$$e_a = \partial_a - \beta_a \partial_3 , \quad e_3 = \partial_3 .$$

# Arbitrary foliation of initial manifold

Initial metric

$$g = g_{ab} dx^a dx^b + \alpha^2 (d\varphi + \beta_a dx^a)^2 .$$

Basis

$$\theta^a = dx^a , \quad \theta^3 = d\varphi + \beta_a dx^a$$

$$e_a = \partial_a - \beta_a \partial_3 , \quad e_3 = \partial_3 .$$

The momentum constraint

$$(|\tilde{g}| T_3^3)_{,3} - \frac{1}{2} |\tilde{g}| g_{ab,3} T^{ab} = 2 |\tilde{g}| \beta_{a,3} T_3^a - \frac{1}{\alpha} e_a (\alpha |\tilde{g}| T_3^a)$$

$$\begin{aligned} (\alpha T_a^b)_{|b} - |\tilde{g}|^{-1} (\alpha |\tilde{g}| T_a^b \beta_b)_{,3} &= (e_a \alpha - \alpha \beta_{a,3}) T_3^3 - \frac{1}{2} \alpha (g_{bc,3} T^{bc}) \beta_a \\ &\quad + \alpha \lambda \eta_{ab} T_3^b - |\tilde{g}|^{-1} (\alpha |\tilde{g}| T_a^3)_{,3} , \end{aligned}$$

where  $\eta^{ab}$  is the Levi-Civita tensor and  $\lambda = \eta^{ab} e_a \beta_b$ .



# Adapted coordinates and functions

Let

$$g = 4\rho^2 d\xi d\bar{\xi} + \alpha^2 (d\varphi + \beta d\xi + \bar{\beta} d\bar{\xi})^2 .$$

# Adapted coordinates and functions

Let

$$g = 4\rho^2 d\xi d\bar{\xi} + \alpha^2 (d\varphi + \beta d\xi + \bar{\beta} d\bar{\xi})^2 .$$

Functions equivalent to  $K_{ij} - \frac{1}{3}Hg_{ij}$ :

$$U = \frac{1}{2}\alpha(T_{11} - T_{22}) + i\alpha T_{12} , \quad V = \alpha(T_{13} + iT_{23}) , \quad W = T_3^3 + \frac{2}{3}H .$$

# Adapted coordinates and functions

Let

$$g = 4\rho^2 d\xi d\bar{\xi} + \alpha^2 (d\varphi + \beta d\xi + \bar{\beta} d\bar{\xi})^2 .$$

Functions equivalent to  $K_{ij} - \frac{1}{3}Hg_{ij}$ :

$$U = \frac{1}{2}\alpha(T_{11} - T_{22}) + i\alpha T_{12} , \quad V = \alpha(T_{13} + iT_{23}) , \quad W = T_3^3 + \frac{2}{3}H .$$

A function of  $V$  and the metric (no  $U$  and  $W$ )

$$E = \rho\alpha^{-1} \text{Re}(2\beta_{,3}V - \partial V) + \frac{2}{3}\rho^3 H_{,3} , \quad \partial = \partial_\xi - \beta\partial_3 .$$

# Adapted coordinates and functions

Let

$$g = 4\rho^2 d\xi d\bar{\xi} + \alpha^2 (d\varphi + \beta d\xi + \bar{\beta} d\bar{\xi})^2 .$$

Functions equivalent to  $K_{ij} - \frac{1}{3}Hg_{ij}$ :

$$U = \frac{1}{2}\alpha(T_{11} - T_{22}) + i\alpha T_{12} , \quad V = \alpha(T_{13} + iT_{23}) , \quad W = T_3^3 + \frac{2}{3}H .$$

A function of  $V$  and the metric (no  $U$  and  $W$ )

$$E = \rho\alpha^{-1} \text{Re}(2\beta_{,3}V - \partial V) + \frac{2}{3}\rho^3 H_{,3} , \quad \partial = \partial_\xi - \beta\partial_3 .$$

A function of  $V$ ,  $W$  and the metric (no  $U$ )

$$F = \frac{1}{2}\rho^2\alpha^{-2}\bar{\partial}(\alpha^3 W) - \frac{3}{2}\rho^2\alpha W\bar{\beta}_{,3} - i\text{Im}(\partial\bar{\beta})V - (\alpha^{-2}\rho^2 V)_{,3} + \frac{2}{3}\rho^2\alpha\bar{\partial}H .$$

## Proposition

*The momentum constraint is equivalent to*

$$(\rho^3 W)_{,3} = E$$

$$U_{,\xi} - (\beta U)_{,3} = F .$$

## Proposition

*The momentum constraint is equivalent to*

$$(\rho^3 W)_{,3} = E$$

$$U_{,\xi} - (\beta U)_{,3} = F .$$

*For analytic data*

$$U = \bar{\chi}_{,3} \left( \int_{\xi_0}^{\xi} d\xi' \frac{F}{\bar{\chi}_{,3}} + h(\bar{\xi}, \bar{\chi}) \right) ,$$

*where  $\beta = \bar{\chi}_{,\xi} / \bar{\chi}_{,3}$  and the integrand is considered as a function of  $\xi'$ ,  $\bar{\xi}$  and  $\bar{\chi}$ .*

## Proposition

The momentum constraint is equivalent to

$$(\rho^3 W)_{,3} = E$$

$$U_{,\xi} - (\beta U)_{,3} = F .$$

For analytic data

$$U = \bar{\chi}_{,3} \left( \int_{\xi_0}^{\xi} d\xi' \frac{F}{\bar{\chi}_{,3}} + h(\bar{\xi}, \bar{\chi}) \right) ,$$

where  $\beta = \bar{\chi}_{,\xi} / \bar{\chi}_{,3}$  and the integrand is considered as a function of  $\xi'$ ,  $\bar{\xi}$  and  $\bar{\chi}$ .

In the nonanalytic case with  $\beta = 0$

$$U = -\frac{1}{4\pi} \int d^2 x' \frac{F(x'^a, \varphi)}{(\bar{\xi}' - \bar{\xi})} + h(\bar{\xi}, \varphi) .$$

If  $U = \hat{U}_{,3}$  and  $F = \hat{F}_{,3}$  then

$$\partial \hat{U} = \hat{F} .$$

Let the CR structure corresponding to  $\partial$  be realizable:  $\partial \bar{\chi} = 0$  and  $\chi \neq f(\xi)$ . Equivalently

$$\beta = \frac{\bar{\chi}_{, \xi}}{\bar{\chi}_{, 3}} .$$

Then

$$\hat{U} = \int_{\xi_0}^{\xi} d\xi' \hat{F}(\xi', \bar{\xi}, \bar{\chi}) + \hat{h}(\bar{\xi}, \bar{\chi})$$

and taking the  $\varphi$ -derivative yields  $U$ .

Formula for  $\beta = 0$  follows from the fundamental solution of the Laplace equation.



Then

$$\partial V = 0 .$$

Equivalently, in terms of real fields and coordinates,

$$T_3^a = \alpha^{-1} \eta^{ab} \omega_{,b} .$$

Other components of  $T^{ij}$  are given in quadrature. In generic case they can be found explicitly but then  $H = 0$  is a differential equation.

Families of data generalizing the Kerr data can be constructed (up to a knowledge of  $\psi$ ).

There exists a class of data (defined in quadrature) which satisfy all constraints but they are not asymptotically flat.

# Hamiltonian constraint for $H' = \text{const}$

# Hamiltonian constraint for $H' = \text{const}$

Given a solution of the momentum constraint with  $H = 0$  we need a conformal factor  $\psi$  which assures that the Hamiltonian constraint is satisfied.

# Hamiltonian constraint for $H' = \text{const}$

Given a solution of the momentum constraint with  $H = 0$  we need a conformal factor  $\psi$  which assures that the Hamiltonian constraint is satisfied.

## Theorem (D. Maxwell)

Let  $(S, g)$  be a complete Riemannian manifold without boundary and let  $(g, K)$  be asymptotically flat data of class  $W_\delta^{k,p}$ .

There exists a unique solution of the Lichnerowicz equation such that  $\psi > 0$  and  $(\psi - 1) \in W_\delta^{k,p}$  if and only if

$$\|f\|_{L^6}^2 \leq \lambda \left( \int_S (8|\nabla f|^2 + Rf^2) dv_g \right), \quad \lambda > 0$$

for all  $f \in C_c^\infty$ .

# Full system of constraints for $H' \neq \text{const}$

$$\Delta\psi = \frac{1}{8}R\psi - \frac{1}{8}K_{ij}K^{ij}\psi^{-7} + \frac{1}{8}H'^2\psi^5$$

$$(\rho^3 W)_{,3} = \frac{2}{3}\psi^6 \rho^3 H'_{,3} + E_0$$

$$U_{,\xi} - (\beta U)_{,3} = \frac{2}{3}\psi^6 \rho^2 \alpha \bar{\partial} H' + F_0$$

where  $E_0$  and  $F_0$  denote  $E$  and  $F$  with  $H = 0$ .

# Alternative approach?

## Alternative approach?

If  $\rho_{,3} = 0$  then

$$(T_3^3)_{,3} = \rho^{-3} E_0$$

defines  $T_3^3$  for given  $V = \alpha(T_{13} + iT_{23})$ .

## Alternative approach?

If  $\rho_{,3} = 0$  then

$$(T_3^3)_{,3} = \rho^{-3} E_0$$

defines  $T_3^3$  for given  $V = \alpha(T_{13} + iT_{23})$ .

Calculate  $H$  from the Hamiltonian constraint

$$R - \tilde{T}_{ab} \tilde{T}^{ab} - 2T_{a3} T^{a3} - 2(T_3^3)^2 - T_3^3 H = 0 .$$



## Alternative approach?

If  $\rho_{,3} = 0$  then

$$(T_3^3)_{,3} = \rho^{-3} E_0$$

defines  $T_3^3$  for given  $V = \alpha(T_{13} + iT_{23})$ .

Calculate  $H$  from the Hamiltonian constraint

$$R - \tilde{T}_{ab} \tilde{T}^{ab} - 2T_{a3} T^{a3} - 2(T_3^3)^2 - T_3^3 H = 0 .$$

Substitute  $H$  and  $T_3^3$  into the equation for  $U$ .

## Alternative approach?

If  $\rho_{,3} = 0$  then

$$(T_3^3)_{,3} = \rho^{-3} E_0$$

defines  $T_3^3$  for given  $V = \alpha(T_{13} + iT_{23})$ .

Calculate  $H$  from the Hamiltonian constraint

$$R - \tilde{T}_{ab} \tilde{T}^{ab} - 2T_{a3} T^{a3} - 2(T_3^3)^2 - T_3^3 H = 0 .$$

Substitute  $H$  and  $T_3^3$  into the equation for  $U$ . If  $\beta = 0$  it reads

$$U_{,\xi} - \rho^2 (fU\bar{U})_{,\bar{\xi}} = h .$$

Functions  $f$  and  $h$  are known and coordinate  $\varphi$  appears as a parameter.



Conformal approach (Maxwell):

- consider initial surface with an internal boundary

Conformal approach (Maxwell):

- consider initial surface with an internal boundary
- complete the Lichnerowicz equation by a boundary condition which assures that the boundary becomes MOTS upon the conformal transformation.

Conformal approach (Maxwell):

- consider initial surface with an internal boundary
- complete the Lichnerowicz equation by a boundary condition which assures that the boundary becomes MOTS upon the conformal transformation.
- prove the inequality

$$\|f\|_{L^6}^2 \leq \lambda \left( \int_S (8|\nabla f|^2 + Rf^2) dv_g - \frac{1}{4} \int_{\partial S} f^2 n^i |_{;i} ds_g \right)$$

Conformal approach (Maxwell):

- consider initial surface with an internal boundary
- complete the Lichnerowicz equation by a boundary condition which assures that the boundary becomes MOTS upon the conformal transformation.
- prove the inequality

$$\|f\|_{L^6}^2 \leq \lambda \left( \int_S (8|\nabla f|^2 + Rf^2) dv_g - \frac{1}{4} \int_{\partial S} f^2 n^i{}_{|i} ds_g \right)$$

- prove existence of the conformal factor  $\psi$

Conformal approach (Maxwell):

- consider initial surface with an internal boundary
- complete the Lichnerowicz equation by a boundary condition which assures that the boundary becomes MOTS upon the conformal transformation.
- prove the inequality

$$\|f\|_{L^6}^2 \leq \lambda \left( \int_S (8|\nabla f|^2 + Rf^2) dv_g - \frac{1}{4} \int_{\partial S} f^2 n^i|_i ds_g \right)$$

- prove existence of the conformal factor  $\psi$

Problems with the existence theorems unless  $K(n, n) = 0$



Conformal approach (Maxwell):

- consider initial surface with an internal boundary
- complete the Lichnerowicz equation by a boundary condition which assures that the boundary becomes MOTS upon the conformal transformation.
- prove the inequality

$$\|f\|_{L^6}^2 \leq \lambda \left( \int_S (8|\nabla f|^2 + Rf^2) dv_g - \frac{1}{4} \int_{\partial S} f^2 n^i|_i ds_g \right)$$

- prove existence of the conformal factor  $\psi$

Problems with the existence theorems unless  $K(n, n) = 0$  and with an extension of initial data through the boundary

Conformal approach (Maxwell):

- consider initial surface with an internal boundary
- complete the Lichnerowicz equation by a boundary condition which assures that the boundary becomes MOTS upon the conformal transformation.
- prove the inequality

$$\|f\|_{L^6}^2 \leq \lambda \left( \int_S (8|\nabla f|^2 + Rf^2) dv_g - \frac{1}{4} \int_{\partial S} f^2 n^i |_{;i} ds_g \right)$$

- prove existence of the conformal factor  $\psi$

Problems with the existence theorems unless  $K(n, n) = 0$  and with an extension of initial data through the boundary (some solutions are constructed in the paper with Józwiowski).

# An approach without boundary

# An approach without boundary

Initial metric induced by the Kerr solution on  $t = \text{const}$

$$g = \rho^2 \Delta^{-1} dr^2 + \rho^2 d\theta^2 + \rho^{-2} \Sigma^2 \sin^2 \theta d\varphi^2$$

where

$$\rho^2 = r^2 + a^2 \cos^2 \theta, \quad \Delta = r^2 - 2Mr + a^2, \quad \Sigma^2 = (r^2 + a^2)^2 - a^2 \Delta \sin^2 \theta.$$

# An approach without boundary

Initial metric induced by the Kerr solution on  $t = \text{const}$

$$g = \rho^2 \Delta^{-1} dr^2 + \rho^2 d\theta^2 + \rho^{-2} \Sigma^2 \sin^2 \theta d\varphi^2$$

where

$$\rho^2 = r^2 + a^2 \cos^2 \theta, \quad \Delta = r^2 - 2Mr + a^2, \quad \Sigma^2 = (r^2 + a^2)^2 - a^2 \Delta \sin^2 \theta.$$

Nonvanishing components of  $T^{ij}$ :

$$T_3^a = \alpha^{-1} \eta^{ab} \omega_{,b},$$

$$\omega = 4aM\rho^{-2} [2(r^2 + a^2) + (r^2 - a^2) \sin^2 \theta] \cos \theta.$$

Conformally flat complex coordinate:  $\xi = (\tilde{r} + i\theta)/2$ , where

$$r = M + \sqrt{M^2 - a^2} \cosh \tilde{r}, \quad \tilde{r} \in [-\infty, \infty]$$

( $\tilde{r} = 0$  is the external Kerr horizon).

## Properties of the data

- $H = 0$
- Invariance under  $\tilde{r} \rightarrow -\tilde{r}$
- $T^{\tilde{i}\tilde{j}}\tilde{r}_{,\tilde{i}}\tilde{r}_{,\tilde{j}} = 0$

## Properties of the data

- $H = 0$
- Invariance under  $\tilde{r} \rightarrow -\tilde{r}$
- $T^{\tilde{i}\tilde{j}}\tilde{r}_{,\tilde{i}}\tilde{r}_{,\tilde{j}} = 0$

They are preserved by the conformal transformation (if  $\psi$  exists and is unique).

## Properties of the data

- $H = 0$
- Invariance under  $\tilde{r} \rightarrow -\tilde{r}$
- $T^{\tilde{r}}_{\tilde{r},i} \tilde{r}_j = 0$

They are preserved by the conformal transformation (if  $\psi$  exists and is unique). Due to this  $\tilde{r} = 0$  is a marginally outer trapped surface (MOTS) for ultimate data.



## Properties of the data

- $H = 0$
- Invariance under  $\tilde{r} \rightarrow -\tilde{r}$
- $T^{\tilde{u}} \tilde{r}_{,i} \tilde{r}_{,j} = 0$

They are preserved by the conformal transformation (if  $\psi$  exists and is unique). Due to this  $\tilde{r} = 0$  is a marginally outer trapped surface (MOTS) for ultimate data.

Solving the momentum constraint with respect to  $U$  and  $W$  under these assumptions is practically impossible because of the condition  $T^{\tilde{u}} n_i n_j = 0$ . Let us try to solve them with respect to  $V$ .

## Proposition

Let

$$g = \rho^2 d\xi d\bar{\xi} + \alpha^2 d\varphi^2, \quad \rho_{,3} = \alpha_{,3} = H = 0$$

and functions  $\rho$ ,  $\alpha$  and  $T^{\dot{i}j}$  be even functions of  $\tilde{r} = \frac{1}{2} \operatorname{Re}\xi$ .

## Proposition

Let

$$g = \rho^2 d\xi d\bar{\xi} + \alpha^2 d\varphi^2, \quad \rho_{,3} = \alpha_{,3} = H = 0$$

and functions  $\rho$ ,  $\alpha$  and  $T^{ij}$  be even functions of  $\tilde{r} = \frac{1}{2} \text{Re}\xi$ .

If  $\text{Re}U$  and  $T_3^3$  satisfy

$$2\text{Re}U - \alpha\rho^2 T_3^3 = 0 \quad \text{at } \tilde{r} = 0$$

## Proposition

Let

$$g = \rho^2 d\xi d\bar{\xi} + \alpha^2 d\varphi^2, \quad \rho_{,3} = \alpha_{,3} = H = 0$$

and functions  $\rho$ ,  $\alpha$  and  $T^{ij}$  be even functions of  $\tilde{r} = \frac{1}{2} \text{Re}\xi$ .

If  $\text{Re}U$  and  $T_3^3$  satisfy

$$2\text{Re}U - \alpha\rho^2 T_3^3 = 0 \quad \text{at} \quad \tilde{r} = 0$$

and  $\text{Im}U$  satisfies

$$\text{Re}((\rho^{-2}\alpha^2 U_{,\xi})_{,\xi}) = \frac{1}{2}(\alpha^3 T_3^3)_{,\xi\bar{\xi}} + \rho^2\alpha^{-2}(\alpha^3 T_3^3)_{,33}$$

## Proposition

Let

$$g = \rho^2 d\xi d\bar{\xi} + \alpha^2 d\varphi^2, \quad \rho_{,3} = \alpha_{,3} = H = 0$$

and functions  $\rho$ ,  $\alpha$  and  $T^{ij}$  be even functions of  $\tilde{r} = \frac{1}{2} \text{Re}\xi$ .

If  $\text{Re}U$  and  $T_3^3$  satisfy

$$2\text{Re}U - \alpha\rho^2 T_3^3 = 0 \quad \text{at } \tilde{r} = 0$$

and  $\text{Im}U$  satisfies

$$\text{Re}((\rho^{-2}\alpha^2 U_{,\xi})_{,\xi}) = \frac{1}{2}(\alpha^3 T_3^3)_{,\xi\bar{\xi}} + \rho^2\alpha^{-2}(\alpha^3 T_3^3)_{,33}$$

then momentum constraint can be solved with respect to  $V$ .

## Proposition

Let

$$g = \rho^2 d\xi d\bar{\xi} + \alpha^2 d\varphi^2, \quad \rho_{,3} = \alpha_{,3} = H = 0$$

and functions  $\rho$ ,  $\alpha$  and  $T^{ij}$  be even functions of  $\tilde{r} = \frac{1}{2} \operatorname{Re}\xi$ .

If  $\operatorname{Re}U$  and  $T_3^3$  satisfy

$$2\operatorname{Re}U - \alpha\rho^2 T_3^3 = 0 \quad \text{at } \tilde{r} = 0$$

and  $\operatorname{Im}U$  satisfies

$$\operatorname{Re}((\rho^{-2}\alpha^2 U_{,\xi})_{,\xi}) = \frac{1}{2}(\alpha^3 T_3^3)_{,\xi\bar{\xi}} + \rho^2\alpha^{-2}(\alpha^3 T_3^3)_{,33}$$

then momentum constraint can be solved with respect to  $V$ . If there exists a unique solution  $\psi$  of the Lichnerowicz equation then the initial data admit a MOTS at  $\tilde{r} = 0$ .

## Proposition

Let

$$g = \rho^2 d\xi d\bar{\xi} + \alpha^2 d\varphi^2, \quad \rho_{,3} = \alpha_{,3} = H = 0$$

and functions  $\rho$ ,  $\alpha$  and  $T^{ij}$  be even functions of  $\tilde{r} = \frac{1}{2} \operatorname{Re}\xi$ .

If  $\operatorname{Re}U$  and  $T_3^3$  satisfy

$$2\operatorname{Re}U - \alpha\rho^2 T_3^3 = 0 \quad \text{at } \tilde{r} = 0$$

and  $\operatorname{Im}U$  satisfies

$$\operatorname{Re}((\rho^{-2}\alpha^2 U_{,\xi})_{,\xi}) = \frac{1}{2}(\alpha^3 T_3^3)_{,\xi\bar{\xi}} + \rho^2\alpha^{-2}(\alpha^3 T_3^3)_{,33}$$

then momentum constraint can be solved with respect to  $V$ . If there exists a unique solution  $\psi$  of the Lichnerowicz equation then the initial data admit a MOTS at  $\tilde{r} = 0$ .

This equation is hyperbolic and coordinate  $\varphi$  enters as a parameter.

# Conclusions



- The Gauss coordinates are not convenient from the point of view of the Hamiltonian constraint.

# Conclusions

- The Gauss coordinates are not convenient from the point of view of the Hamiltonian constraint.
- For analytic data or reduced number of free functions the momentum constraint can be solved in quadrature and the conformal method can be applied if  $H = 0$ .

- The Gauss coordinates are not convenient from the point of view of the Hamiltonian constraint.
- For analytic data or reduced number of free functions the momentum constraint can be solved in quadrature and the conformal method can be applied if  $H = 0$ .
- The algebraic method of solving the Hamiltonian constraint and the construction of a generalized Kerr data with MOTS are (perhaps) worth studying.

- The Gauss coordinates are not convenient from the point of view of the Hamiltonian constraint.
- For analytic data or reduced number of free functions the momentum constraint can be solved in quadrature and the conformal method can be applied if  $H = 0$ .
- The algebraic method of solving the Hamiltonian constraint and the construction of a generalized Kerr data with MOTS are (perhaps) worth studying.
- More work needed to include multiple horizons.